KALIKADEVI ART'S, COMMERCE \& SCIENCE COLLEGE, SHIRUR(KA)


# Numerical Integration of Partial Differential Equations (PDEs) 

- Introduction to PDEs.
- Semi-analytic methods to solve PDEs.
- Introduction to Finite Differences.
-Stationary Problems, Elliptic PDEs.
- Time dependent Problems.
-Complex Problems in Solar System Research.


## Introduction to PDEs.

- Definition of Partial Differential Equations.
- Second Order PDEs.
-Elliptic
-Parabolic
-Hyperbolic
- Linear, nonlinear and quasi-linear PDEs.
- What is a well posed problem?
- Boundary value Problems (stationary).
- Initial value problems (time dependent


## Differential Equations

- A differential equation is an equation for an unknown function of one or several variables that relates the values of the function itself and of its derivatives of various orders.
- Ordinary Differential Equation:

Function has 1 independent variable.

- Partial Differential Equation: At least 2 independent variables.


## Physical systems are often described by coupled Partial Differential Equations (PDEs)

- Maxwell equations
- Navier-Stokes and Euler equations in fluid dynamics.
- MHD-equations in plasma physics
- Einstein-equations for general relativity


## PDEs definitions

- General (implicit) form for one function $u(x, y)$ :
$F\left(x, y, u(x, y), \frac{\partial u(x, y)}{\partial x}, \frac{\partial u(x, y)}{\partial y}, \ldots, \frac{\partial^{2} u(x, y)}{\partial x \partial y}, \ldots\right)=0$,
- Explicit PDE => We can resolve the equation to the highest derivative of $u$.
- Linear PDE => PDE is linear in $u(x, y)$ and for all derivatives of $u(x, y)$
- Semi-linear PDEs are nonlinear PDEs, which are linear in the highest order derivative.


## PDEs and Quadratic Equations

- Quadratic equations in the form

$$
A x^{2}+B x y+C y^{2}+D x+E y+F=0
$$

$$
\begin{aligned}
& a(x, y) c(x, y)-b(x, y) 2 / 4>0 \text { Ellipse } \\
& a(x, y) c(x, y)-b(x, y) 2 / 4=0 \text { Parabola } \\
& a(x, y) c(x, y)-b(x, y) 2 / 4<0 \text { Hyperbola }
\end{aligned}
$$

With coordinate transformations these equations can be written in the standard forms:
Ellipse: $\quad \frac{x^{2}}{a^{2}}+\frac{y^{2}}{b^{2}}=1$
Parabola: $y^{2}=4 a x$
Hyperbola: $\frac{x^{2}}{a^{2}}-\frac{y^{2}}{b^{2}}=1$

Coordinate transformations can be also applied to get rid of the mixed derivatives in PDEs. (For space dependent coefficients this is only possible locally, not globally)

## Second Order PDEs with more then

## 2 independent variables

$$
L u=\sum_{i=1}^{n} \sum_{j=1}^{n} a_{i, j} \frac{\partial^{2} u}{\partial x_{i} \partial x_{j}}
$$

plus lower order terms $=0$.

## Classification by eigenvalues of the coefficient matrix:

- Elliptic: All eigenvalues have the same sign. [Laplace-Eq.]
- Parabolic: One eigenvalue is zero. [Diffusion-Eq.]
- Hyperbolic: One eigenvalue has opposite sign. [Wave-Eq.]
- Ultrahyperbolic: More than one positive and negative eigenvalue.

Mixed types are possible for non-constant coefficients, appear frequently in science and are often difficult to solve.

## Elliptic Equations

- Occurs mainly for stationary problems.
- Solved as boundary value problem.
- Solution is smooth if boundary conditions allow.

Example: Poisson and Laplace-Equation ( $\mathrm{f}=0$ )

$$
\begin{gathered}
\nabla^{2} \Phi=f \\
\sum_{i=1}^{n} \frac{\partial^{2}}{\partial x_{i}^{2}} \Phi(x)=f(x)
\end{gathered}
$$

## Parabolic Equations

- The vanishing eigenvalue often related to time derivative.
- Describes non-stationary processes.
- Solved as Initial- and Boundary-value problem.
- Discontinuities / sharp gradients smooth out during temporal evolution.


## Example: Diffusion-Equation, Heat-conduction

$$
\frac{\partial}{\partial t} u(x, t)=a \cdot \frac{\partial^{2}}{\partial x^{2}} u(x, t)
$$

$$
\frac{\partial}{\partial t} u(\vec{r}, t)=a \cdot \Delta u(\vec{r}, t)
$$

- The opposite sign eigenvalue is often related to the time derivative.
- Initial- and Boundary value problem.
- Discontinuities / sharp gradients in initial state remain during temporal evolution.
- A typical example is the Wave equation.

$$
c^{2} \frac{\partial^{2} u}{\partial x^{2}}=\frac{\partial^{2} u}{\partial t^{2}}
$$



## Ill-conditioned problems

- Even well posed problems can be ill-conditioned.
- => Small changes (errors,noise) in data lead to large errors in the solution.
- Can occur if continuous problems are solved approximately on a numerical grid. PDE => algebraic equation in form $A x=b$
- Condition number of matrix $A$ :

$$
\kappa(A)=\left|\frac{\lambda_{\max }(A)}{\lambda_{\min }(A)}\right|
$$

are maximal and minimal eigenvalues of $A$.
 low $\lambda_{\text {max }}(A), \lambda_{\text {min }} A$ ilumber.

## How to solve PDEs?

- PDEs are solved together with appropriate Boundary Conditions and/or Initial Conditions.
- Boundary value problem -Dirichlet B.C.: Specify $u(x, y, \ldots)$ on boundaries (say at $x=0, x=L x, y=0, y=L y$ in a rectangular box) -von Neumann B.C.: Specify normal gradient of $u(x, y, \ldots)$ on boundaries.
In principle boundary can be arbitrary shaped.
(but difficult to implement in computer codes)



## -Initial value problem

- Boundary values are usually specified on all boundaries of the computational domain.
- Initial conditions are specified in the entire computational (spatial) domain, but only for the initial time $t=0$.
- Initial conditions as a Cauchy problem:
-Specify initial distribution $u(x, y, \ldots, t=0)$
[for parabolic problems like the Heat equation]
- Specify $u$ and du/dt for $t=0$
[for hyperbolic problems like wave equation.]


## Initial value problem

$$
\begin{aligned}
& \text { initial values }
\end{aligned}
$$

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## Semi-analytic methods to solve PDEs.

- From systems of coupled first order PDEs (which are difficult to solve) to uncoupled PDEs of second order.
- Example: From Maxwell equations to wave equation.
- (Semi) analytic methods to solve the wave equation by separation of variables.
- Exercise: Solve Diffusion equation by separation of variables.


## How to obtain uncoupled 2. order PDEs from physical laws?

- Example: From Maxwell equations to wave equations.
- Maxwell equations are a coupled system of first order vector PDEs.
- Can we reformulate this equations to a more simple form?
- Here we use the electromagnetic potentials, vectorpotential and scalar potential.

