#### KALIKADEVI ART'S, COMMERCE & SCIENCE COLLEGE, SHIRUR(KA)



# DEPARTMENT OF MATHEMATICS

Numerical Integration of Partial Differential Equations (PDEs)

# Introduction to PDEs.

- Semi-analytic methods to solve PDEs.
- Introduction to Finite Differences.
- Stationary Problems, Elliptic PDEs.
- Time dependent Problems.
- Complex Problems in Solar System Research.

Introduction to PDEs.

- Definition of Partial Differential Equations.
- Second Order PDEs.
  - -Elliptic
  - -Parabolic
  - -Hyperbolic
- Linear, nonlinear and quasi-linear PDEs.
- What is a well posed problem?
- Boundary value Problems (stationary).
- Initial value problems (time dependent)

## **Differential Equations**

- A differential equation is an equation for an unknown function of one or several variables that relates the values of the function itself and of its derivatives of various orders.
- Ordinary Differential Equation: Function has 1 independent variable.
- Partial Differential Equation: At least 2 independent variables.

Physical systems are often described by coupled Partial Differential Equations (PDEs)

Maxwell equations

. . .

- Navier-Stokes and Euler equations in fluid dynamics.
- MHD-equations in plasma physics
- Einstein-equations for general relativity

#### **PDEs definitions**

► General (implicit) form for one function u(x,y) :

$$F\left(x, y, u(x, y), \frac{\partial u(x, y)}{\partial x}, \frac{\partial u(x, y)}{\partial y}, \dots, \frac{\partial^2 u(x, y)}{\partial x \partial y}, \dots\right)$$

- Explicit PDE => We can resolve the equation to the highest derivative of u.
- Linear PDE => PDE is linear in u(x,y) and for all derivatives of u(x,y)
- Semi-linear PDEs are nonlinear PDEs, which are linear in the highest order derivative.

= 0

### PDEs and Quadratic Equations

Quadratic equations in the form

$$Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$$

a(x,y)c(x,y) - b(x,y)2 / 4 > 0 Ellipse a(x,y)c(x,y) - b(x,y)2 / 4 = 0 Parabola a(x,y)c(x,y) - b(x,y)2 / 4 < 0 Hyperbola With coordinate transformations these equations can be written in the standard forms:

Ellipse: 
$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

Parabola: 
$$y^2 = 4ax$$

Hyperbola: 
$$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$$

Coordinate transformations can be also applied to get rid of the mixed derivatives in PDEs. (For space dependent coefficients this is only possible locally, not globally)

# Second Order PDEs with more then 2 independent variables

 $Lu = \sum_{i=1}^{n} \sum_{j=1}^{n} a_{i,j} \frac{\partial^2 u}{\partial x_i \partial x_j} \quad \text{ plus lower order terms} = 0.$ 

#### **Classification by eigenvalues of the coefficient matrix:**

- Elliptic: All eigenvalues have the same sign. [Laplace-Eq.]
- Parabolic: One eigenvalue is zero. [Diffusion-Eq.]
- Hyperbolic: One eigenvalue has opposite sign. [Wave-Eq.]
- Ultrahyperbolic: More than one positive and negative eigenvalue.

Mixed types are possible for non-constant coefficients, appear frequently in science and are often difficult to sølve.

## **Elliptic Equations**

- Occurs mainly for stationary problems.
- Solved as boundary value problem.
- Solution is smooth if boundary conditions allow.

#### Example: Poisson and Laplace-Equation (f=0)

$$\nabla^2 \Phi = f$$
$$\sum_{i=1}^n \frac{\partial^2}{\partial x_i^2} \Phi(x) = f(x)$$

## Parabolic Equations

- The vanishing eigenvalue often related to time derivative.
- Describes non-stationary processes.
- Solved as Initial- and Boundary-value problem.
- Discontinuities / sharp gradients smooth out during temporal evolution.

#### Example: Diffusion-Equation, Heat-conduction

$$\frac{\partial}{\partial t}u(x,t) = a \cdot \frac{\partial^2}{\partial x^2}u(x,t)$$

 $\overset{\smile}{\overline{\partial t}} u(\vec{r},t) = a \cdot \Delta u(\vec{r},t)$ 

# Hyperbolic Equations

- The opposite sign eigenvalue is often related to the time derivative.
- Initial- and Boundary value problem.
- Discontinuities / sharp gradients in initial state remain during temporal evolution.
- A typical example is the Wave equation.

$$c^2 \frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 u}{\partial t^2}$$

With nonlinear terms involved sharp gra evolution => Shocks  $-\frac{1}{c^2}\frac{\partial}{\partial t^2}$ 

# Ill-conditioned problems

- Even well posed problems can be **ill-conditioned**.
- Small changes (errors, noise) in data lead to large errors in the solution.
- Can occur if continuous problems are solved approximately on a numerical grid. PDE => algebraic equation in form Ax = b
- **Condition number** of matrix A:

$$\kappa(A) = \left| \frac{\lambda_{\max}(A)}{\lambda_{\min}(A)} \right|$$

are maximal and minimal eigenvalues of A.

• Well conditioned problems have a low condition of number.

## How to solve PDEs?

PDEs are solved together with appropriate Boundary Conditions and/or Initial Conditions.

 Boundary value problem
Dirichlet B.C.: Specify u(x,y,...) on boundaries (say at x=0, x=Lx, y=0, y=Ly in a rectangular box)
-von Neumann B.C.: Specify normal gradient of u(x,y,...) on boundaries.

In principle boundary can be arbitrary shaped.

(but difficult to implement in computer codes)



# Initial value problem

- Boundary values are usually specified on all boundaries of the computational domain.
- Initial conditions are specified in the entire computational (spatial) domain, but only for the initial time t=0.
- Initial conditions as a Cauchy problem:

-Specify initial distribution u(x,y,...,t=0) [for parabolic problems like the Heat equation]

 Specify u and du/dt for t=0 [for hyperbolic problems like wave equation.]

#### Initial value problem



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#### Semi-analytic methods to solve PDEs.

- From systems of coupled first order PDEs (which are difficult to solve) to uncoupled PDEs of second order.
- Example: From Maxwell equations to wave equation.
- (Semi) analytic methods to solve the wave equation by separation of variables.
- Exercise: Solve Diffusion equation by separation of variables.

# How to obtain uncoupled 2. order PDEs from physical laws?

- Example: From Maxwell equations to wave equations.
- Maxwell equations are a coupled system of first order vector PDEs.
- Can we reformulate this equations to a more simple form?
- Here we use the electromagnetic potentials, vectorpotential and scalar potential.